

Eigenvalues and Eigenvectors

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Type	Feature	Eigen-values	Eigenvectors	Deduction
Symmetric	$S^T = S = Q\Lambda Q^T = Q\Lambda Q^{-1}$	\mathbb{R}	Orthogonal $x_i^T x_j = 0$	<p>\mathbb{R} eigenvalues: $Sv = \lambda v \Leftrightarrow \lambda \langle v, v \rangle = \langle \lambda v, v \rangle = \langle Sv, v \rangle = v^T S^T v = v^T \lambda v = \langle v, \lambda v \rangle = \bar{\lambda} \langle v, v \rangle \Leftrightarrow \lambda = \bar{\lambda} \Leftrightarrow \lambda \in \mathbb{R}$</p> <p>Orthogonal eigenvectors: $Sx = \lambda_1 x \wedge Sy = \lambda_2 y \wedge \lambda_1 \neq \lambda_2 \Leftrightarrow \lambda_1 \langle x, y \rangle = \langle \lambda_1 x, y \rangle = x^T S^T y = x^T \lambda_2 y = \lambda_2 \langle x, y \rangle \Leftrightarrow x^T y = 0$</p>
Orthogonal (Unitary)	$Q^T = Q^{-1} (\bar{Q}^T = Q^{-1})$	$ \lambda = 1$	Orthogonal $\bar{x}_i^T x_j = 0$	<p>If S is unitary, then the length of its eigenvalues are 1. Conversely, if S has n orthonormal eigenvectors e_i whose eigenvalues are all of length 1, then S is unitary. If $v = \sum_{i=1}^n c_i e_i$ and $Sv = \lambda v$, then $\ v\ ^2 = \langle v, v \rangle = \sum_{i=1}^n c_i^2$, $\ Sv\ ^2 = \langle Sv, Sv \rangle = \sum_{i=1}^n (c_i \lambda_i)^2 = \sum_{i=1}^n (c_i)^2 = \ v\ ^2$, the length remains after transformation.</p>
Skew-symmetric	$A^T = -A$	$\mathbb{C} \setminus \mathbb{R}$	Orthogonal $\bar{x}_i^T x_j = 0$	<p>$\mathbb{C} \setminus \mathbb{R}$ eigenvalues: $Sv = \lambda v \Leftrightarrow \lambda \langle v, v \rangle = \langle \lambda v, v \rangle = \langle Sv, v \rangle = v^T S^T v = -v^T \lambda v = \langle v, \lambda v \rangle = -\bar{\lambda} \langle v, v \rangle \Leftrightarrow \lambda = -\bar{\lambda} \Leftrightarrow \lambda \in \mathbb{C} \setminus \mathbb{R}$</p>
Complex Hermitian	$\bar{S}^T = S$	\mathbb{R}	Orthogonal $\bar{x}_i^T x_j = 0$	Complex Symmetric Matrix.
Positive Definite	<p>(i) pivots > 0 (ii) n upper determinants > 0 (iii) $\lambda > 0$ (iv) $x^T S x > 0 (x \neq 0)$ (v) $S = A^T A, \det A \neq 0$</p>	\mathbb{R}^+	Orthogonal	<p>$S^T = S$ (iv) is the basic definition (energy test) (iv) \Rightarrow (iii) Use Vice Proof, $\exists \lambda \leq 0, Sv = \lambda v \Rightarrow v^T Sv = \lambda v^T v = \lambda \ v\ ^2 \leq 0!$ and (iii) \Rightarrow (iv) $\lambda_i > 0, S = Q\Lambda Q^T; x^T S x = x^T Q\Lambda(x^T Q)^T = x'^T \Lambda x' = \sum_{i=1}^n \lambda_i x_i^2 > 0$ (i) \Leftrightarrow (iii) follows from Sylvester's law of Inertia. (iii) \Leftrightarrow (iv) Mathematical induction (iv) \Rightarrow (v) $S = Q\Lambda Q^T = Q\sqrt{\Lambda}\sqrt{\Lambda}Q^T = Q\sqrt{\Lambda}(Q\sqrt{\Lambda})^T$ (v) \Rightarrow (iv) $S = A^T A, x^T S x = x^T A^T A x = \ Ax\ ^2 > 0 (\det A \neq 0)$</p>
Positive Semi-definite	(i) pivots ≥ 0	$\mathbb{R}^+ \cup \{0\}$	Orthogonal	Notice the restriction is deleted.

	(ii) n upper determinants ≥ 0 (iii) $\lambda \geq 0$ (iv) $x^T Sx \geq 0 (x \neq 0)$ (v) $S = A^T A$			
Negative definite	(i) pivots ≤ 0 (ii) even upper determinants > 0 , Odd upper determinants < 0 (iii) $\lambda \leq 0$ (iv) $x^T Sx \leq 0 (x \neq 0)$ (v) $S = -A^T A$	$\mathbb{R}^- \cup \{0\}$	Orthogonal	For (ii), A is Negative definite, means $-A$ is positive definite! Minor of $-A$ is greater than 0, then when it comes to even – rank, it's positive for A ; when it is odd – rank, it's negative for A ! $(-1)^n$
Markov	$m_{ij} > 0, \sum_{i=1}^n m_{ij} = 1$	$\lambda_{max} = 1$	Steady state $x > 0$	Lemma M^k is also a Markov matrix. The first property is obvious. Then the second property, $u_1 = Mu_0$, $u_0 \geq 0$ and the sum of u_0 is 1, use column formula, u_1 's sum is also 1. Then M^k is also a Markov matrix. Pf If $\exists \lambda > 1$, then M^k will blow up, doesn't fit the property (sum is 1). (10.3)
Similar	$A = BCB^{-1}$	$\lambda(A) = \lambda(C)$ (if and only if)	$Bv(C)$	$Cv = \lambda v \Rightarrow BCv = \lambda Bv \Rightarrow A(Bv) = \lambda(Bv)$ Transitive: $C = XEX^{-1} \Rightarrow A = X'EX'^{-1}$
Projection	$P = P^2 = P^T$	1 0	Column space Null space	Projection on the column space stays the same.
Plane Rotation	$Q = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$	$e^{-i\theta}$ $e^{i\theta}$	$(1, i)$ $(1, -i)$	$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 1 \\ i \end{pmatrix} = \begin{pmatrix} \cos \theta - i \sin \theta \\ \sin \theta + i \cos \theta \end{pmatrix} = \begin{pmatrix} e^{-i\theta} \\ ie^{-i\theta} \end{pmatrix} = e^{-i\theta} \begin{pmatrix} 1 \\ i \end{pmatrix}$
Reflection	$R = I - 2uu^T (\ u\ = 1)$	-1 1 : 1	u Whole plane u^\perp	$(I - 2uu^T)u = u - 2u = -u$ $v^T u = 0 \Rightarrow (I - 2uu^T)v = v$

Rank One	uv^T	$v^T u$ 0 \vdots 0	u Whole plane v^\perp	$uv^T u = u(v^T u) = (v^T u)u$ $w^T v = 0 \Rightarrow uv^T w = u(v^T w) = 0$
Inverse	A^{-1}	$\frac{1}{\lambda(A)}$	$v(A)$	$Av = \lambda v \Rightarrow \frac{1}{\lambda} v = A^{-1}v$
Shift	$A + cI$	$\lambda(A) + c$	$v(A)$	$Av = \lambda v \wedge cIv = cv \Rightarrow (A + cI)v = (\lambda + c)v$
Stable Powers	$A^n \rightarrow 0 (n \rightarrow \infty)$	$ \lambda < 1$	\forall	$A = X\Lambda X^{-1} \Rightarrow A^n = X\Lambda^n X^{-1} (\lambda^n \rightarrow 0, n \rightarrow \infty)$ When not diagonalizable, use Perturbation
Stable Exponential	$e^{At} \rightarrow 0 (t \rightarrow \infty)$	$\text{Re } \lambda < 0$	\forall	$A = X\Lambda X^{-1} \Rightarrow e^{At} = X e^{\Lambda t} X^{-1} (\lambda^t \rightarrow 0, t \rightarrow \infty)$ When not diagonalizable, use Perturbation
Cyclic Permutation	$P_{i,i+1} = 1, P_{n1} = 1$ $P_3 = \begin{pmatrix} & & 1 \\ & 1 & \\ 1 & & \end{pmatrix}$	$\lambda_k = e^{\frac{2\pi i k}{n}}$ = roots of 1	$x_k = (1, \lambda_k, \dots, \lambda_k^{n-1})$	Eigenvalues are roots of 1 $\det(P - \lambda I) = 0 \iff (-\lambda)^n + (-1)^{n-1} = 0 \iff \lambda^n = 1$
Circulant	$c_0 I + c_1 P + \dots$	λ_k = c_0 + $c_1 e^{\frac{2\pi i k}{n}}$	$x_k = (1, \lambda_k, \dots, \lambda_k^{n-1})$	FFT (Fast Fourier Transform)
Tridiagonal	-1, 2, -1 on diagonals	λ_k = 2 - $2 \cos \frac{k\pi}{n+1}$	x_k = $\left(\sin \frac{k\pi}{n+1}, \sin \frac{2k\pi}{n+1}, \dots \right)$	By guessing and verifying
Diagonalizable	$A = X\Lambda X^{-1}$	Diagonal of Λ	Columns of X are independent	Diagonalizable condition: A has n independent eigenvectors. (if and only if) Geometric Multiplicity = Algebraic Multiplicity GM = AM Lemma If A has n different eigenvalues, then it has n independent eigenvectors. If not, we can select the <u>minimal</u> linearly dependent eigenvectors. We can assume that $v_k = \sum_{i=1}^{k-1} c_i v_i$, where $c_i \neq 0$. Then $Av_k = \lambda_k v_k = \sum_{i=1}^{k-1} \lambda_k c_i v_i$ and $Av_k = A\left(\sum_{i=1}^{k-1} c_i v_i\right) = \sum_{i=1}^{k-1} \lambda_i c_i v_i$, where $v_i (i = 1, 2, \dots, k-1)$ are

				linearly independent. And the same vector has two different forms based on the same basis, which is impossible.
Schur	$A = QTQ^{-1}$, T is triangular	Diagonal of T	Columns of Q , if $A^T A = AA^T$	*Schur's Triangularization
Frobenius companion	$D_{i,i+1} = 1, D_{nj} = a_{j-1}$	$\lambda_1, \dots, \lambda_n$ are known	$x_k = (1, \lambda_k, \dots, \lambda_k^{n-1})$	Differential Equation $u_{k+n} = a_{n-1}u_{k+n-1} + \dots + a_1u_{k+1} + a_0u_k$ with initial condition u_0, u_1, \dots, u_{n-1} are known. $v_k = D^k v_0 = D^k \begin{pmatrix} u_0 \\ \vdots \\ u_{n-1} \end{pmatrix}, D^k = X\Lambda^k X^{-1}$ And output u_{k+n-1} . Use the method of standing-by coefficients. And from the diagonalization, we can know that the power of the eigenvalue shares the same value k.
Congruent	$A = BCB^T$, B is invertible	#(positive, zero, negative) index is equal		Sylvester's law of Inertia If and only if positive, negative, zero index for A and C are equal. The proof*
Normal	$\bar{N}^T N = N\bar{N}^T, N = Q\Lambda\bar{Q}^T$	$ \lambda = 1$	Orthonormal vectors in Q	Proof 1 (i) $N = QTQ^*$, find $T^*T = TT^*$ (ii) $T = \begin{pmatrix} a & b \\ & d \end{pmatrix}, b=0$ (iii) $2 \rightarrow n$ Proof 2 $U = TT^*, V = T^*T, U(1,1) = V(1,1)$ $U(1,1) = \sum_j T(1,j)T^*(j,1) = \sum_j T(1,j) ^2$ $V(1,1) = \sum_j T^*(1,j)T(j,1) = \sum_j T(j,1) ^2 = T(1,1) ^2$ $\sum_{j=2}^n T(1,j) ^2 = 0 \Leftrightarrow T(1,j) = 0 (j \geq 2)$ The same for other rows. Then T is diagonal.
*Jordan				

*SVD				
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1. A and B are diagonalizable, then $AB = BA \iff A$ and B share all n eigenvectors.
2. $AB = BA \Rightarrow A$ and B share at least 1 eigenvector. (not necessarily diagonalizable)
3. $f(A) = Xf(\Lambda)X^{-1}$
4. (Cayley-Hamilton Theorem) $p_A(A) = 0$